RIOT-Lab

How to use RIOT in the IoT-Lab

Oliver "Oleg" Hahm

INRIA

October 15, 2015

Agenda

1. Prepare for a RIOT
   - Prepare your Toolchain
   - Obtain the Code
   - Understanding RIOT
2. Using RIOT on native and the Testbed
   - Working with an Example
   - Using an IPv6 Application
3. Writing an Application for RIOT
   - Setting up the Application
   - Some helpful Features
   - Get your Hands dirty
4. Join the RIOT

Slides are online available at http://riot-os.org/files/2015-riotlab-tutorial.pdf.

Agenda

Recommended Build Environment

- For the IoT-Lab nodes we recommend to use *gcc-arm-embedded toolchain*.
  It can be found on https://launchpad.net/gcc-arm-embedded.
- A quick guide to install the proper toolchain can be found in the RIOT wiki:
  http://wiki.riot-os.org/Setup-a-Build-Environment
- See also http://wiki.riot-os.org/Board:-IoT-LAB-M3 for particular information on RIOT on the IoT-Lab nodes.
- For the *native* port you have to install 32bit libraries.
  See http://wiki.riot-os.org/Family:-native#toolchains

Github

```
git clone https://github.com/RIOT-OS/RIOT.git && \
cd RIOT && git checkout 2015.09
```

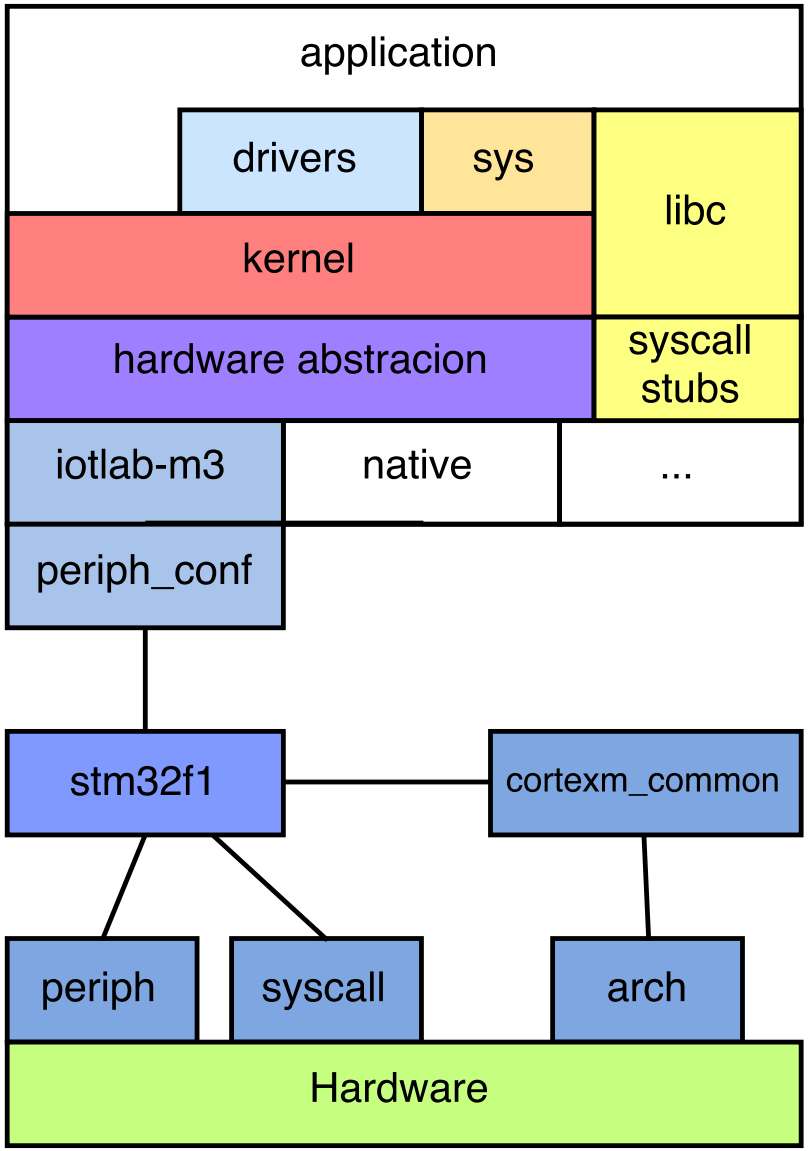
or download the zipped version:
https://github.com/RIOT-OS/RIOT/archive/2015.09.zip

The braver among you may also try the development version...

As a small fix for CLI-tools and getting rid of some warnings please go to
`~/iot-lab/parts/cli-tools` and type
`sudo pip install -e .[secure]`.

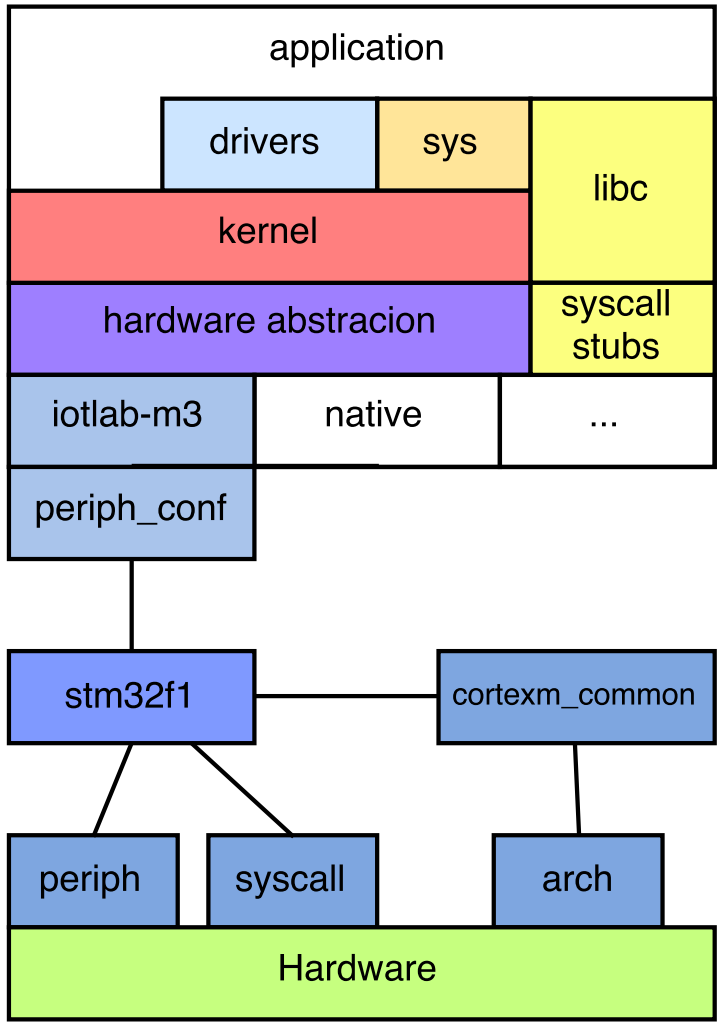
github
SOCIAL CODING

The Architecture



The Folder Structure

```
RIOT
├── boards
│   └── iotlab-m3
├── core
├── cpu
│   ├── cortexm_common
│   └── stm32f1
├── dist
├── doc
├── drivers
│   ├── at86rf231
│   └── isl29020
├── examples
│   └── hello-world
├── pkg
│   └── libcoap
├── sys
│   └── net
│       └── gnrc
└── tests
```



Best Practice for RIOT programming

- Dos
  - Use static memory
  - Select the priorities carefully
  - Minimize stack usage with `DEVELHELP` and `CREATE_STACKTEST`
  - Use threads
- Donts
  - Don't use threads
  - Don't use the POSIX wrapper if implementing something from scratch
- Consult the Wiki: http://wiki.riot-os.org
- ...and the API documentation: http://doc.riot-os.org

Best Practice for RIOT programming

- Dos
  - Use static memory
  - Select the priorities carefully
  - Minimize stack usage with `DEVELHELP` and `CREATE_STACKTEST`
  - Use threads
    Increase flexibility, modularity, and robustness by using IPC.
- Donts
  - Don't use threads
    Try not to use more than one thread per module.
    Don't create threads for one-time tasks.
  - Don't use the POSIX wrapper if implementing something from scratch
- Consult the Wiki: http://wiki.riot-os.org
- ...and the API documentation: http://doc.riot-os.org

Agenda

Compile and run on *native*

Let's prepare a simple, virtual network:

```
[RIOT]# dist/tools/tapsetup/tapsetup -c 2
creating tapbr0
creating tap0
creating tap1
```

Now we build and start the first virtual node.

```
[RIOT]# cd examples/default/
[default]# make all term
Building application default for native w/ MCU native.
"make" -C /home/oleg/git/RIOT/cpu/native
...
RIOT native board initialized.
RIOT native hardware initialization complete.

main(): This is RIOT! (Version: 2015.09-tbilisi-HEAD)
Native RTC initialized.
Welcome to RIOT!
> help
Command              Description
---------------------------------------
reboot               Reboot the node
ps                   Prints information about running threads.
rtc                  control RTC peripheral interface
ifconfig             Configure network interfaces
txtsnd               send raw data
```

Setup the second Node

Ok, how about a second node?
Therefore, we specify the *tap* interface to use by (re-)using the `PORT` environment variable. We can use any created *tap* interface from the previous step. (Default is *tap0*.) Once the node has started, we check its radio address.

```
[default]# PORT=tap1 make term
Welcome to RIOT!
> ifconfig
Iface  4   HWaddr: 8a:c2:b6:72:eb:57
           Source address length: 6
```

Connecting the two Nodes

It's time to send our first packet (assuming that the first node is still running.). Go back to the first node and type:

```
> txtsnd 4 8a:c2:b6:72:eb:57 riotlab
```

On the second node we should see something like:

```
PKTDUMP: data received:
~~ SNIP  0 - size:   7 byte, type: NETTYPE_UNDEF (0)
000000 72 69 6f 74 6c 61 62
~~ SNIP  1 - size:  20 byte, type: NETTYPE_NETIF (-1)
if_pid: 4  rssi: 0  lqi: 0
src_l2addr: a6:b7:d0:ea:de:f9
dst_l2addr: 8a:c2:b6:72:eb:57
~~ PKT    -  2 snips, total size:  27 byte
```

Using the same example on the testbed

Running the same example on a real node is very similar.
We use the environment variable `BOARD` to specify the target platform – and `IOTLAB_` variables for testbed configuration.

```
[default]# BOARD=iotlab-m3 IOTLAB_SITE=lille IOTLAB_DURATION=60 make all
    iotlab-exp
Building application "default" for "iotlab-m3" with MCU "stm32f1"
"make" -C /tmp/RIOT/boards/iotlab-m3
...
Waiting that experiment 29409 gets in state Running
"Running"
```

And now connect to the nodes using the serial_aggregator:

```
[default]# BOARD=iotlab-m3 IOTLAB_SITE=lille make iotlab-term
Connection to lille.iot-lab.info closed.
1444752645.849845;Aggregator started
ifconfig
1444752749.523268;m3-13;ifconfig
1444752749.523673;m3-9;ifconfig
1444752749.525317;m3-9;Iface  4  HWaddr: 9d:12  Channel: 26  NID: 0x23
    TX-Power: 0dBm  State: IDLE CSMA Retries: 4
1444752749.525976;m3-13;Iface  4  HWaddr: 96:16  Channel: 26  NID: 0x23
     TX-Power: 0dBm  State: IDLE CSMA Retries: 4
...
```

The Shell in a Nutshell

- For this step we will use *gnrc_networking* application from examples directory.
- You can configure RIOT to provide you with some default system shell commands.
- All available shell commands and some online help are shown by calling `help`:

```
> help
help
Command              Description
---------------------------------------
udp                  send data over UDP and listen on UDP ports
reboot               Reboot the node
ps                   Prints information about running threads.
ping6                Ping via ICMPv6
mersenne_init        initializes the PRNG
mersenne_get         returns 32 bit of pseudo randomness
ifconfig             Configure network interfaces
txtsnd               send raw data
fibroute             Manipulate the FIB (info: 'fibroute [add|del]')
ncache               manage neighbor cache by hand
routers              IPv6 default router list
rpl                  rpl configuration tool [help|init|rm|root|show]
```

The selection of commands depends on the configuration of your application (and may vary a little bit for different platforms).

Let's communicate

The *gnrc_networking* application provides you with some helpful shell commands:

1. ping: The famous ICMP diagnosis tool (system command).
2. udp: A very basic command for arbitrary UDP connections (application command).

After we flashed two nodes, we'll have to find out their IPv6 addresses using `ifconfig`:

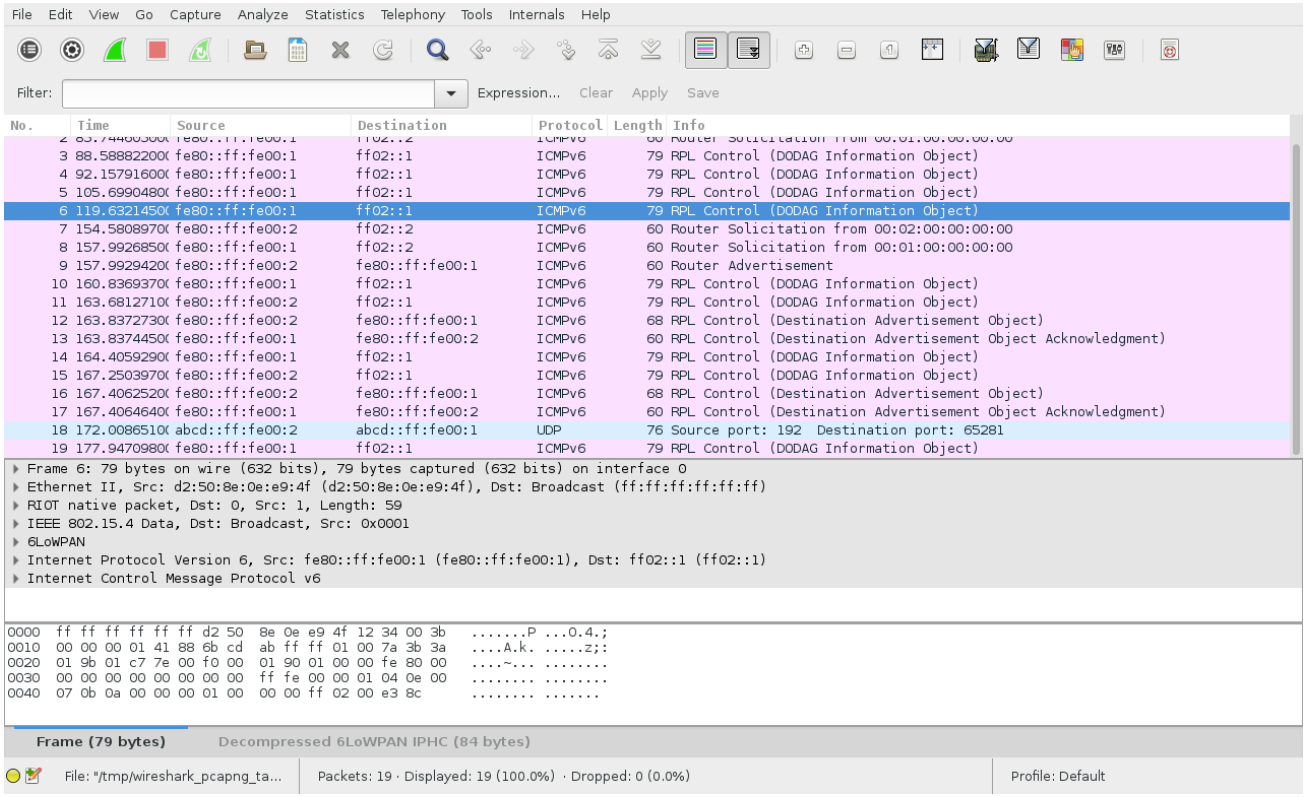
```
    m3-66;ifconfig
Iface  7   HWaddr: 7f:06  Channel: 26  NID: 0x23  TX-Power: 0dBm  State: IDLE
      CSMA Retries: 4
   Long HWaddr: 36:32:48:33:46:d8:7f:06
   AUTOACK  CSMA  MTU:1280  6LO  IPHC
   Source address length: 8
   Link type: wireless
   inet6 addr: ff02::1/128  scope: local [multicast]
   inet6 addr: fe80::3432:4833:46d8:7f06/64  scope: local
   inet6 addr: ff02::1:ffd8:7f06/128  scope: local [multicast]
```

Now we can try to ping the other node:

```
> ping fe80::ff:fe00:f01e
INFO # ping fe80::ff:fe00:f01e
INFO # Echo reply from fe80::ff:fe00:f01e received, rtt: 0.0340s
```

Virtualize your Network

- You can also monitor the traffic with *Wireshark*.
- There's a python framework to setup arbitrary topologies using defined loss-rates: http://wiki.riot-os.org/Virtual-riot-network



Agenda

The Makefile

To create your own RIOT example, you need only two files:

1. A C (or C++) file with a main function
2. A Makefile

You can find a template for a Makefile in `dist/Makefile`.

```
# Giving your application a name
APPLICATION = riotlab1
# Choosing a default platform
BOARD ?= native
# Specifying the RIOT folder
RIOTBASE ?= $(CURDIR)/../../RIOT
# Some helpful compiler flags
CFLAGS += -DSCHEDSTATISTICS -DDEVELHELP
# Quieten the building process
QUIET ?= 1
# Modules to include:
USEMODULE += posix
USEMODULE += xtimer
USEMODULE += shell_commands
# Let RIOT's build system take care of the rest
include $(RIOTBASE)/Makefile.include
```

The main() Function

The only mandatory thing in your application is a `main` function with this prototype:

```
int main(void)
```

Standard C libraries can be used and parts of POSIX are ble through a wrapper within RIOT.

```
#include <stdio.h>
#include <unistd.h>

#define WAIT_USEC    (1000 * 1000)

int main(void)
{
    puts("Hello!");
    usleep(WAIT_USEC);
    puts("Good night!");

    return 0;
}
```

Doing it the RIOT way

Instead of POSIX functions is usually advisable (and more efficient) to just use the native RIOT functions:

```
#include <stdio.h>
#include "xtimer.h"


int main(void)
{
    puts("Let's throw a brick!");
    xtimer_usleep(SEC_IN_USEC);
    puts("System terminated");

    return 0;
}
```

Starting the Shell

```
#include "shell_commands.h"

static int my_echo(int argc, char **argv);
...
const shell_command_t shell_commands[] = {
    {"echo", "Echo the user's input", my_echo},
    {NULL, NULL, NULL}
};
...
/* allocate some memory for the input line */
char line_buf[SHELL_DEFAULT_BUFSIZE];
/* starting the shell loop (blocking) */
shell_run(shell_commands, line_buf, SHELL_DEFAULT_BUFSIZE);
```

Threads and IPC

```
/* allocate memory for the thread's stack */
char my_stack[THREAD_STACKSIZE_MAIN];
/* define a function as entry point for your new thread */
void *my_thread(void *arg) {
...
kernel_pid_t pid = thread_create(my__stack, sizeof(my_thread_stack),
                                 THREAD_PRIORITY_MAIN - 1, CREATE_STACKTEST,
                                 my_thread, NULL, "mythread");

msg_t m;
m.content.value = 1;
msg_send_receive(&m, &m, pid);
```

Now it's up to you

Your task is now to extend the *sixlowapp* example.

- Check the source code of the `posix_sockets` example and API documentation online: http://doc.riot-os.org
- Check the documentation for the sensor API, e.g. for the light sensor: http://doc.riot-os.org/group__driver__isl29020.html
- Initialize all four sensors in the beginning of the application.
- Extend the netcat command to send optionally measured sensor data.
- Print the measurements on the receiving side.

Agenda

Where to get help

- Mailing Lists
  - devel@riot-os.org
  - users@riot-os.org
- IRC on irc.freenode.org, #riot-os
- Regular video conferencing meetings

Thank you!
Any questions?